

Compact Set Neighboring Relation and Its Application in the Evaluating the Evolution Tree

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Abstract For evaluating the quality of a evolution tree reconstructed by computer, the neighboring relations consist with original distances are very important. However, the neighboring relations are not equally important. In this paper, from a relative point of view, we propose an estimating criterion that neighboring relations with respect to compact sets, those neighboring relations are more important. We estimate the evolution tree with considering whether those relations are consist or not. In the last part of the paper, we estimate some famous programs of constructing evolution tree with using the criterion on real data.

Key Words: computational biology , compact set , evolution tree , heuristic algorithm

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1 INTRODUCTION

The purposes for studying phylogenetics include (1) reconstructing the correct genealogical ties between species and (2) estimating the time when a divergence occurs between species from a common ancestor. These usually can be done by constructing trees, whose leaves represent present-day species and whose interior nodes represent hypothesized ancestors. Trees of this kind are called *evolution trees*. When an evolution tree is constructed from a distance matrix, the distances should be properly reflected. Usually, the criterion is that all of the distances in the tree reflect the original distances among species. That is, when two species are close to each other in the distance matrix, they should be close to each other in the evolution tree. The following object functions give us different evolution trees, and each criterion corresponds to a distinct evolution tree problem. We use $\mathcal{D}_{\mathcal{T}}(i, j)$ to denote the path length from specie i to specie j in the evolution tree \mathcal{T} and $\mathcal{D}(i, j)$ to denote the distance between species i and j in the input distance matrix \mathcal{D} .

1. Minimax

In a minimax evolution tree, the maximum of $\mathcal{D}_{\mathcal{T}}(i, j) - \mathcal{D}(i, j)$ is minimized.

2. Minisum

In a minisum evolution tree, the total sum of all pairs of distances among leaf nodes is minimized.

3. Minimize

In a minimize evolution tree, the total length of the tree is minimized.

These *absolute* object functions are insufficient for constructing evolution trees. That is, new evolutionary relations between species defined by a evolution tree with good minisum may conflict with those defined by the original distance matrix \mathcal{D} . Or, there are two evolution trees with the same minimize, yet it is hard to determine which one is better? From the output result, we cannot measure the details of the topology of a tree.

So we propose an objective function, compact set neighboring relation , and use it to work out the *preserved neighboring ratio*. We describe a new optimization

problem below and its hardness is still open.

Maximum Preserved Neighboring Ratio

INSTANCE: A distance matrix D over label set S .

QUESTION: Finding the evolution tree T labeled by S with maximum preserved ratio.

We introduce the definition of neighboring relation, compact set, and compact set neighboring relation in section 2. In section 3 we present our algorithm used to generate the compact set neighboring relations and the calculation of preserved neighboring ratio. In section 4 we show the experimental result.

2 Preliminaries

2.1 Neighboring Relation

Given a set S of n sequences, we use a symmetric $n \times n$ matrix D to denote the distance matrix of S and $D(i, j)$ to denote the distance between sequence i and j in D . That is, all the elements in D are nonnegative, $D(i, i) = 0$ and $D(i, j) = D(j, i)$ for any $i, j \in S$. D is *metric* if the distances obey the triangle inequality, i.e. $D(i, j) + D(j, k) > D(i, k)$ for any $i, j, k \in S$.

For any sequences $i, j, k \in S$, let $((i, j), k)$ denote the relation $D(i, j) \leq \min\{D(i, k), D(j, k)\}$. For any sequences i, j in a tree \mathcal{T} , we use $\text{LCA}(i, j)$ to denote the least common ancestor of i and j in \mathcal{T} . For any sequences i, j and k , there is a *neighboring relation* in \mathcal{T} if and only if the relations $((i, j), k)$ and $(\text{LCA}(i, j) < \text{LCA}(i, k) = \text{LCA}(j, k))$ exist.

2.2 Compact Sets

Given a set $S = \{S_1, S_2, \dots, S_N\}$ of N sequences, we use $D(S_i, S_j)$ to denote the distance between S_i and S_j in the distance matrix D . We also can represent this instance by a connected undirected graph $G = (V, E)$, such that V is S and each edge (S_i, S_j) in E is associated with a weight $D(S_i, S_j)$. For any subset C of S , C is called a *compact set* if the distance between elements in C and elements not in C is larger than the longest distance in C , i.e., $\min\{D(S_i, S_j) | S_i \in C, S_j \in S \setminus C\} > \max\{D(S_i, S_j) | S_i \in C, S_j \in C\}$. In other words, the sequences of a compact set are closer to each other than to other sequences. By definition, S is a compact set and each set consisting of single sequence is also a compact set (i.e., these compact sets are trivial). Consider the distance matrix of Figure 1 as an example. It is not hard to see that there are three nontrivial compact sets $\{S_1, S_6\}$, $\{S_1, S_2, S_6\}$ and $\{S_3, S_4, S_5\}$ among the sequences.

The relation among the compact sets can be represented in tree with using the following property:

LEMMA 2.1 ([1]). *Let A and B be two different compact sets of S . If $A \cap B \neq \emptyset$, then either $A \subset B$ or $B \subset A$.*

D	S_1	S_2	S_3	S_4	S_5	S_6
S_1	0	10	16	18	13	8
S_2		0	14	17	15	9
S_3			0	9	10	12
S_4				0	9	19
S_5					0	11
S_6						0

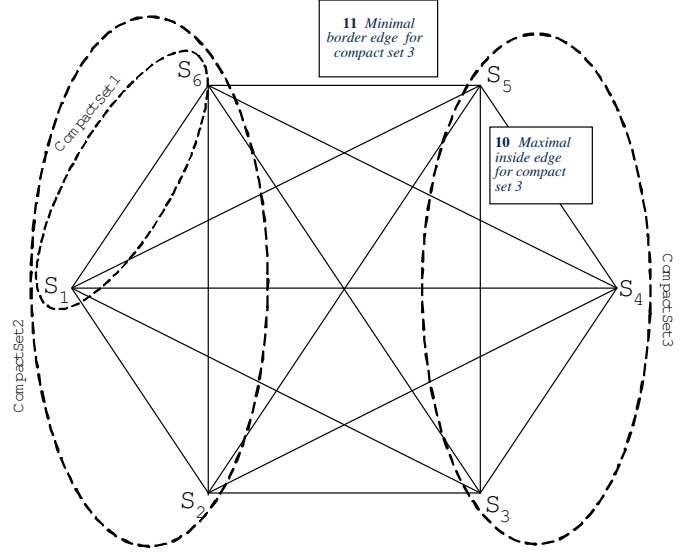


Figure 1. A distance matrix D for 5 sequences and its compact set tree with three nontrivial compact sets $\{S_1, S_6\}$, $\{S_1, S_2, S_6\}$ and $\{S_3, S_4, S_5\}$.

Given a compact set A of S such that $A \neq S$, we consider the smallest size compact set C_A that properly contains A . According to Lemma 2.1, C_A is unique. Since, if two different compact sets of S have non-empty intersection. For example, they both contain the compact set A . According to Lemma 2.1, one properly contains the other, so the smallest size compact set containing A is unique. We represent the containment relationship of these compact sets by a graph $\mathcal{T}_C = (V_{\mathcal{T}_C}, E_{\mathcal{T}_C})$, such that $V_{\mathcal{T}_C}$ is the set of all compact sets and each edge (A, C_A) in $E_{\mathcal{T}_C}$ links a compact set A to the set C_A . Clearly, \mathcal{T}_C is a rooted tree, in which the root represents the compact set S , each of its leaves represents a compact set of single sequence of S , and each internal node represents the union of the compact sets represented by its children. Given \mathcal{T}_C , the compact sets can be found by traversing \mathcal{T}_C in postorder and unioning the compact set represented by the children to obtain their parent's compact set. Here, we call \mathcal{T}_C as a *compact set tree* of S (see Figure ?? for example). For example, we can represent the compact set in Figure ?? as $\{\{S_3, S_4, S_5\}, \{\{S_1, S_6\}, S_2\}\}$.

2.3 Compact Set Neighboring Relation

Let \mathcal{C} be the sets of all compact sets of S . For any three species $S_i, S_j, S_k \in S$, if there is a compact set C of \mathcal{C} such that $S_i, S_j \in C$ and $S_k \notin C$, then we say

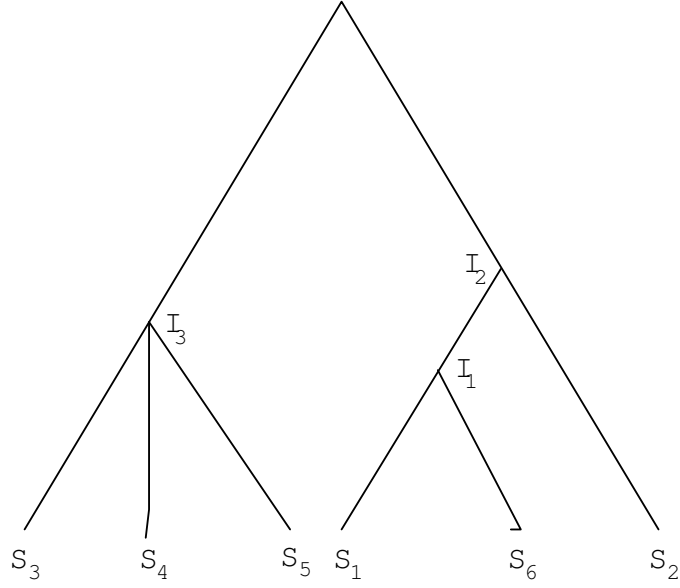


Figure 2. The compact set tree \mathcal{T}_C of above distance matrix D with three internal nodes I_1 , I_2 , and I_3 representing compact sets $\{S_1, S_6\}$, $\{S_1, S_2, S_6\}$, and $\{S_3, S_4, S_5\}$ respectively.

that these three sequences have the *compact set neighboring relation*, and denote it by $((S_i, S_j), S_k) \in \mathcal{N}_C$. Let \mathcal{R} be the sets of all three sequences in S possessing the neighboring relations with respect to \mathcal{C} , i.e., $\mathcal{R} = \{((S_i, S_j), S_k) | ((S_i, S_j), S_k) \in \mathcal{N}_C\}$.

3 The Implementation

Before we find all compact set neighboring relations, we should know all the compact sets. we use Kim's algorithm[2] to find all compact sets, then start our algorithm. Our algorithm is composed of two stages:

1. Generate the neighboring relations \mathcal{R} of \mathcal{C} and $\mathcal{R}_{\mathcal{T}}$ from $\mathcal{D}_{\mathcal{T}}$.
2. Calculate the set-difference of \mathcal{R} and $\mathcal{R}_{\mathcal{T}}$.

3.1 Stage 1

When given a \mathcal{C} , the bellow algorithm generates the total *compact set neighboring relations*.

Algorithm 1: Compact Set Neighboring Relations

Input: Given \mathcal{C} be a compact set of $S = \{S_1, S_2, \dots, S_n\}$ represented as brackets.

Output: The total compact set neighboring relations.

begin

```

1 | NR-STACK =NULL ;
  | PARESE-CS(S) *Construct a compact set tree  $\mathcal{T}_{\mathcal{C}}$  from  $\mathcal{C}$  ;
  | for each child  $v$  of root( $\mathcal{T}_{\mathcal{C}}$ ) do
  |   |  $\perp$  NERCOM ( $S, v$ ) ;
  | end

```

Let \mathcal{C}_v be the compact set belonging to the node v of the compact set tree $\mathcal{T}_{\mathcal{C}}$. We now describe the subroutine NERCOM (s, v):

Procedure PARESE-CS(s)

```
begin
  repeat
    switch  $\mathcal{W} = \text{getc}(s)$  do
      case {
        | Push  $\mathcal{W}$  into STACK ;
      case Species
        | Push  $\mathcal{W}$  into STACK ;
      case }
        1. Pop the species from STACK until the top of STACK is {.
        2. Pop {.
        3. Create a new internal node  $I$  and assign the species popped in step1 as
           children.
        4. Push  $I$  into STACK.
    until Reading to the end of  $s$ ;
end
```

Procedure NERCOM(s, v)

```
begin
   $C_{out} = s \setminus C_v$  ;
  NR-STACK  $\leftarrow ((S_i, S_j), S_k)$ , for all  $S_i, S_j \in C_v$  and  $S_k \in C_{out}$  ;
  for each child  $u$  of  $v$  and  $u$  isn't a leave do
    | NERCOM ( $C_v, u$ ) ;
end
```

For example, the input compact set is represented as $\{\{S_3, S_4, S_5\}, \{\{S_1, S_6\}, S_2\}\}$.

Its compact set tree \mathcal{T}_C can be obtained after running step 1, like shown in Figure ???. The root node of \mathcal{T}_C contains of two children I_2 and I_3 so two subroutines NERCOM (S, I_2) and NERCOM (S, I_3) are called respectively. In subroutine NERCOM (S, I_2), it generates neighboring relation listed in Table 1. Because internal node I_2 contains of a child, I_1 , another subroutine NERCOM (C_{v_2}, I_1) is called. Neighboring

I_2	I_1	I_3
$((S_1, S_2), S_3)$	$((S_1, S_6), S_2)$	$((S_3, S_4), S_1)$
$((S_1, S_2), S_4)$		$((S_3, S_4), S_2)$
$((S_1, S_2), S_5)$		$((S_3, S_4), S_6)$
$((S_1, S_6), S_3)$		$((S_3, S_5), S_1)$
$((S_1, S_6), S_4)$		$((S_3, S_5), S_2)$
$((S_1, S_6), S_5)$		$((S_3, S_5), S_6)$
$((S_2, S_6), S_3)$		$((S_4, S_5), S_1)$
$((S_2, S_6), S_4)$		$((S_4, S_5), S_2)$
$((S_2, S_6), S_5)$		$((S_4, S_5), S_6)$

Table 1. The neighboring relation in internal nodes I_2, I_1 and I_3 .

relation generated in this subroutine is also listed in Table 1. We note that it does not generate duplicate neighboring relation been generated in its parent. In subroutine `NERCOM` (S, I_3) , it is the same. The respective C_v and C_{out} of each internal node are shown in Figure 3.

There are n species popped and pushed in the procedure `PARESE-CS`. Because each couple brackets merges at least one species, there are at most $O(n)$ couple brackets popped and pushed in `PARESE-CS`. The number of internal node popped and pushed is also at most $O(n)$. Combining above analysis, we have the cost of step 1 is $O(n)$. In the procedure `NERCOM`, it generates every neighboring relation only once. Therefore, denoting by p the number of compact set neighborong relations, we have that the total work of `NERCOM` is $O(p)$. Combining this two results, we have

THEOREM 3.1. *The total neighboring relation with respect to \mathcal{C} can be generated in time $O(n + p)$.*

3.2 Stage 2

Given a topology of \mathcal{T} , we can list a linear inequality satisfying that the path length between leaves i and j on \mathcal{T} is larger than or equal to $D(i, j)$, for any two $i, j \in V$. Then, we can get $D_{\mathcal{T}}$ by solving the linear programming minimizing the tree size. For any three sequences $i, j, k \in V$, if $D_{\mathcal{T}}(i, j) \leq \min\{D_{\mathcal{T}}(i, k), D_{\mathcal{T}}(j, k)\}$, then we say that these three sequences have the *neighboring relation* with respect

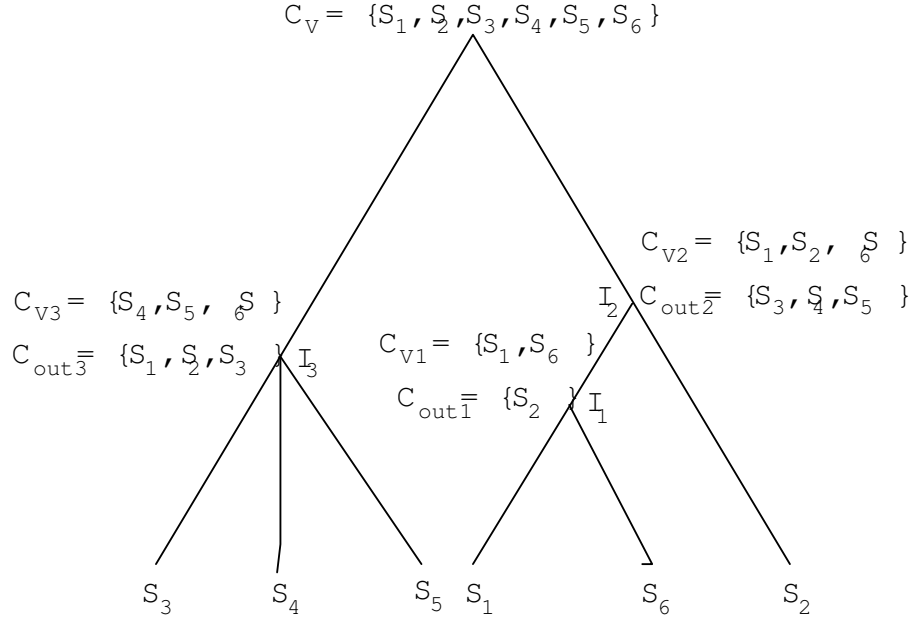


Figure 3. The respective C_v and C_{out} of each internal node.

to \mathcal{T} , and denote it by $((i, j), k) \in \mathcal{N}_{\mathcal{T}}$. Let $R_{\mathcal{T}}$ be the sets of all three sequences in V possessing the neighboring relation with respect to \mathcal{T} . Then we define the *preserved neighboring ratio* of T to be $\mathcal{P}(\mathcal{T}) = \frac{|\mathcal{R} \cap \mathcal{R}_{\mathcal{T}}|}{|\mathcal{R}|}$.

4 Experimental Results

We choose the two algorithms NJA and GA with some real data, then calculate their preserved neighboring ratio.

The data sets we use in the experiment are as follow and their r are smaller than 30.

1. The first data set, denoted by PROTEIN12, consists of 12 protein sequences with length 80–160 residues.
2. The second data set, denoted by DNA28, consists of 28 DNA sequences of fruit flies with length 800–900 nucleotides.
3. The third, fourth, fifth and sixth data set, denoted by HUMAN34-1, HUMAN34-2, HUMAN34-3 and HUMAN34-4 respectively, each of them consists of 34 DNA sequences of human mitochondria with length 660–690 nucleotides.
4. The other 5 data sets are selected from the BALiBASE [4, 5] benchmark alignment database, denoted by 1vln(4), 1ycc(4), 2abk(4), 1pysA(5) and 2cba(5) with length 118–236, 105–190, 211–344, and 234–328, respectively, where the number in the brackets denotes which reference sets this data set belongs to. 1vln(4) and 2cba(5) consist of 14 and 8 sequences, respectively. However, we have to remove some sequences from the original data sets such that the program can successfully output result. 1ycc(8) has 8 sequences, which is the same as BALiBASE except sequence 1etp; 2abk(4) has 5 sequences, which is the same as BALiBASE except sequence 1MPGA; 1pysA(5) has 7 sequences, which is the same as BALiBASE except sequence 1aszB, 1adjA and 1lylA.

Our experimental flow chart is shown as Figure 4.

Table 2 shows the preserved neighboring ratios of T_{Kru} and NJ. In this case, the trees almost have the equal number of outperformance.

Data	NJA	GA
PROTEIN12	41.35%	41.35%
DNA28	59.57%	73.48%
HUMAN34-1	80.50%	90.50%
HUMAN34-2	79.66%	82.63%
HUMAN34-3	65.34%	85.96%
HUMAN34-4	82.70%	81.45%
1vln(4)	38.37%	53.49%
1ycc(4)	52.94%	23.53%
2abk(4)	60.00%	30.00%
1pysA(5)	65.52%	48.28%
2cba(5)	42.50%	32.50%

Table 2. The results of preserved compact-set ratio.

5 CONCLUSIONS AND FUTURE WORK

From the topology viewpoint, we propose a new measurement of preserved neighboring ratio to evaluate the quality of evolution tree. When there are two evolution trees with the same or similar tree size, we may choose the one with the larger preserved neighboring ratio. In the following, we propose some open problems concerning our compact set evaluation.

1. Can we classify the neighboring relations with respect to compact set according to the height of least common ancestor ?
2. When there are few non-trivial compact sets, can we relax compact set restrictions? For example, any inside is less than border edge multiplying a constant number.

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