# Hamiltonian Problems on Ptolemaic Graphs * 

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#### Abstract

This paper gives a unified approach for solving the Hamiltonian path, the Hamiltonian cycle problems and their variants on Ptolemaic graphs. These algorithms run in linear time.


## 1 Introduction

All graphs in this paper are finite, undirected, without loops or multiple edges. Let $G=(V, E)$ be a graph with $|V|=n$ and $|E|=m$. A connected graph is called Ptolemaic if and only if for any four vertices $x, y, z, w$ of it we have the Ptolemaic inequality $d(x, y) d(z, w) \leq d(x, z) d(y, w)+d(x, w) d(y, z)$. Properties and optimization problems of Ptolemaic graphs have been studied in $[2,9,15,16,20,23,18]$. These graphs are superclasses of block graphs and subclasses of distance-hereditary graphs. A Hamiltonian path (respectively, cycle) of a graph $G$ is a simple path (respectively, cycle) containing all vertices of $G$. The Hamiltonian path (respectively, cycle) problem is to determine whether a graph $G$ has a Hamiltonian path (respectively, cycle) or not. This two problems are NPcomplete for general graphs [13]. We will use the notations $H C, H P,(H P, s)$ and $(H P, s, t)$ as abbreviations

[^0]for "Hamiltonian cycle", "Hamiltonian path", "Hamiltonian path with endpoint $s$ " and "Hamiltonian path with endpoints $s$ and $t^{\prime \prime}$, respectively. Nicolai [20] presented the first polynomial-time algorithms for determining whether or not a Ptolemaic graph has an $H P$ in $O\left(n^{2}(n+m)\right)$ time, an $(H P, s)$ in $O(n(n+m))$ time, an $(H P, s, t)$ in $O(n+m)$ time, an $H C$ in $O(n+m)$ time, for any $s, t \in V$, provided a d-extremal dismantling scheme is given (see [20] for definition). Whereas computing a $d$-extremal dismantling scheme requires $O\left(n^{2}\right)$ time [20] in a general graph. Though, most recently Dragan and Nicolai [11] presented a lineartime algorithm for computing such a $d$-extremal dismantling scheme on Ptolemaic graphs. They first gave an algorithm for the Hamiltonian cycle problem and then solved the Hamiltonian path problems by reducing them to the Hamiltonian cycle problem. It seems that exists a more efficient and unified algorithm for these Hamiltonian problems on Ptolemaic graphs if we avoid the use of $d$-extremal dismantling scheme and exploit the structure of Ptolemaic graphs. In this paper we give a unified approach to determine whether or not a Ptolemaic graph $G$ has a $H C, H P,(H P, s)$ or ( $H P, s, t$ ) simultaneously in linear time. Our algorithm sharpens Nicolai's idea and does not use the $d$ extremal dismantling scheme. Notice that a graph $G$ is Ptolemaic if and only if it is distance-hereditary and chordal [2, 9, 15, 16]. A graph is distance-hereditary if and only if every two vertices have the same distance in
every connected induced subgraph $[2,9,14]$. Distancehereditary graphs have been studied in $[1,2,4,5,9$, $10,12,14,15,16,19,21,22,23,24,6,7]$. A graph is chordal if every cycle of length $>3$ has a chord. A graph is a cograph if there is no induced path containing 4 vertices.

## 2 Preliminaries

In this paper the terminology and notation of Bondy and Murty [3] are followed. Suppose $A$ and $B$ are two sets of vertices in a graph $G=(V, E) . G[A]$ denotes the subgraph of $G$ induced by $A$. The neighborhood $N_{A}(B)$ of $B$ in $A$ is the set of vertices in $A$ that are adjacent to some vertex in $B$. The closed neighborhood $N_{A}[B]$ of $B$ in $A$ is $N_{A}[B] \bigcup B$. For simplicity, $N_{A}(v), N_{A}[v], N(B)$, and $N[B]$ stand for $N_{A}(\{v\})$, $N_{A}[\{v\}], N_{V}(B)$, and $N_{V}[B]$, respectively. The distance $d_{G}(x, y)$ or $d(x, y)$ between two vertices $x$ and $y$ in $G$ is the minimum length of an $x-y$ path in $G$. The hanging $h_{u}$ of a connected graph $G=(V, E)$ at a vertex $u \in V$ is the collection of sets $L_{0}(u), L_{1}(u), \ldots$, $L_{t}(u)$ (or $L_{0}, L_{1}, \ldots, L_{t}$ if there is no ambiguity), where $t=\max _{v \in V} d_{G}(u, v)$ and $L_{i}(u)=\{v \in V$ : $\left.d_{G}(u, v)=i\right\}$ for $0 \leq i \leq t$. For any $1 \leq i \leq t$ and any vertex $v \in L_{i}$, let $N^{\prime}(v)=N(v) \bigcap L_{i-1}$. A vertex $v \in L_{i}$ with $1 \leq i \leq t$ has a minimal neighborhood in $L_{i-1}$ if $N^{\prime}(w)$ is not a proper subset of $N^{\prime}(v)$ for any $w \in L_{i}$. For two disjoint vertex subsets $X, Y$ of a graph $G=(V, E)$, they are said to be joint if each vertex of $X$ is adjacent to each vertex of $Y$.

Notice that a Ptolemaic graph is chordal and distance-hereditary. In the following theorem several characterizations of distance-hereditary graphs and Ptolemaic graphs are stated, which are useful to our algorithm

Theorem $1[2,9,14]$ Suppose $h_{u}=\left(L_{0}, L_{1}, \ldots, L_{t}\right)$ is a hanging of a connected distance-hereditary graph $G$ at $u$.
(1) For any two vertices $x, y \in L_{i}, 1 \leq i \leq t$, we have that $N^{\prime}(x)$ and $N^{\prime}(y)$ are either disjoint, or one of the two sets is contained in the other. Moreover, if $G$ is Ptolemaic then every $N^{\prime}(x)$ induces a complete graph of $G$.
(2) There exists a vertex $v \in L_{i}$ such that $v$ has a minimal neighborhood in $L_{i-1}$. In addition, if $v$ satisfies the above condition then for every pair of vertices $x$ and $y$ in $N^{\prime}(v)$, we have $N_{V-N^{\prime}(v)}(x)=N_{V-N^{\prime}(v)}(y)$.
(3) For every pair of vertices $x, y \in L_{i}, 1 \leq i \leq t$, that are in the same component of $G\left[V-L_{i-1}\right]$, we have $N^{\prime}(x)=N^{\prime}(y)$.
(4) Every $L_{i}$ induces a cograph in $G$.

The following observation is the base of our algorithms: In Theorem 1, suppose $t>1$, let $Y$ be a component of $G\left[L_{t}\right]$ with $\left|N_{L_{t-1}}(Y)\right| \leq\left|N_{L_{t-1}}(B)\right|$ for every component $B$ in $G\left[L_{t}\right]$. Let $X=N_{L_{t-1}}(Y)$ and $Z=N[X]-(X \cup Y)$. It is clear that $X, Y$ and $Z$ are disjoint sets with $N[Y] \subseteq(X \cup Y)$ and $N[X] \subseteq(X \cup Y \cup Z)$. ¿From Theorem 1(3) and the choice of $Y$ we note that any vertex in $Y$ has a minimal neighborhood in $L_{t-1}$, meanwhile $X$ and $Y$ are joint. Therefore by Theorem 1(2) $X$ and $Z$ are joint. Moreover $X$ will induce a complete subgraph of $G$ when $G$ is a Ptolemaic graph.

## 3 Hamiltonian Problems

Throughout this section, $X, Y$, and $Z$ will denote three nonempty disjoint vertex subsets of a graph $G=(V, E)$ with $N[Y] \subseteq(X \cup Y)$ and $N[X] \subseteq(X \cup Y \cup Z)$ such that $X$ and $Y$ are joint, $X$ and $Z$ are joint, and $X$ induces a complete subgraph of $G, Y$ induces a cograph. An $H P$ (respectively, $H C,(H P, s),(H P, s, t)$ with $|\{s, t\} \cap Y| \leq 1$ is $(X, Y)$-canonical if it contains a subpath that visits all vertices in $Y$ and no vertices in $V-(X \cup Y)$. An hamiltonian path $\mathcal{P}$ which is an $(H P, s, t)$ having $\{s, t\} \subseteq Y$ is $(X, Y)$-canonical if $\mathcal{P}=P_{1} P_{2} P_{3}$ such that (i) $P_{1}$ starts from $s$, (ii) $P_{3}$ ends at $t$, (iii) $P_{1}$ and $P_{3}$ do not visit any vertex in $V-(X \cup Y)$, (iv) $P_{2}$ does not visit any vertex in $Y$, and (v) either $P_{1}$ or $P_{3}$ has all its vertices in $Y$. For a graph $H, \pi_{0}(H)$ denotes the minimum number of pairwise disjoint paths covering $H, \pi_{1}(H, s)$ denotes the minimum number of pairwise disjoint paths covering $H$ such that $s$ is endpoint of one of these paths, and $\pi_{2}(H, s, t)$ denotes the minimum number of pairwise disjoint paths covering $H$ such that $s$ and $t$ are endpoints of two of these paths, or $\pi_{2}(H, s, t)=1$ if $H$ contains an $H P$ with endpoints $s$ and $t$. For notational convenience we will use $\pi_{0}(Y), \pi_{1}(Y, s)$ and $\pi_{2}(Y, s, t)$ to denote $\pi_{0}(G[Y]), \pi_{1}(G[Y], s)$ and $\pi_{2}(G[Y], s, t)$ respectively. We say that a subpath $P^{\prime}$ of a path $P$ is an $(X, Y)$-path if $P^{\prime}$ starts from a vertex in $X$, ends at a vertex in $Y$, and has all its vertices in $X \cup Y$. A subpath $P^{\prime}$ of a path $P$ is $(X, Y)$-maximal if $P^{\prime}$ is an $(X, Y)$-path and is not a proper subpath of any $(X, Y)$ path of $P$. For a subset $W$ of vertices of a graph $G$, we say that a subpath $P$ is a $(W)$-path if $P$ has all its vertices in $W$. A subpath $P^{\prime}$ of a path $P$ is $(Y)$-maximal if $P^{\prime}$ is a $(Y)$-path and is not a proper subpath of any $(Y)$-path of $P$. Suppose $P=p_{1} p_{2} \cdots p_{k}$ is a path and $p_{i}$ 's are vertices visited by path $P$ in the ordering that path $P$ visits them. The reverse path of $P$, denoted by $\bar{P}$, is the path that visits vertices $p_{i}$ 's for all $1 \leq i \leq k$ in the reverse ordering that path $P$ visits them.

Lemma 2 If $G$ has an ( $H P, s, t$ ), then $G$ has an $(X, Y)$-canonical $(H P, s, t)$.

Proof. Suppose $\mathcal{P}$ is an $(H P, s, t)$ of $G$. If $\mathcal{P}$ has no $(X, Y)$-path, then it starts from vertex $s \in Y$ and visits all vertices in $Y$ before it visits any vertex not in $Y$. Clearly, it is an $(X, Y)$-canonical $(H P, s, t)$. Thus, we assume that $\mathcal{P}$ has an $(X, Y)$-path. Let $\left\{P_{x y}^{i}: 1 \leq\right.$ $i \leq k\}$ be the set of all $(X, Y)$-maximal subpaths of $\mathcal{P}$. Without loss of generality, assume that $t \in Y$ if $|Y \cap\{s, t\}| \geq 1$. Then, there are four cases:
Case $1, \mathcal{P}=P_{s} P_{x y}^{1} P_{x z}^{1} P_{x y}^{2} P_{x z}^{2} \ldots P_{x z}^{k-1} P_{x y}^{k} P_{t}$,
Case $2, \mathcal{P}=P_{x y}^{1} P_{x z}^{1} P_{x y}^{2} P_{x z}^{2} \ldots P_{x z}^{k-1} P_{x y}^{k} P_{t}$,
Case $3, \mathcal{P}=P_{s} P_{x y}^{1} P_{x z}^{1} P_{x y}^{2} P_{x z}^{2} \ldots P_{x z}^{k-1} P_{x y}^{k}$, and
Case 4, $\mathcal{P}=P_{x y}^{1} P_{x z}^{1} P_{x y}^{2} P_{x z}^{2} \ldots P_{x z}^{k-1} P_{x y}^{k}$.
Clearly, each path $P_{x z}^{i}$ starts from a vertex in $X$, ends at a vertex in $Z$, and has all its vertices in $V-Y$ for all $i, 1 \leq i<k$.
Case 1. Since we assume that $t \in Y$ if $|Y \cap\{s, t\}| \geq$ 1, therefore $s \notin Y$ in this case. Otherwise, $t \in Y$ and hence $P_{t}$ will contain an $(X, Y)$-maximal path, a contradiction. Thus, both paths $P_{s}$ and $P_{t}$ do not visit any vertex in $Y, P_{s}$ ends at a vertex in $Z$, and $P_{t}$ starts from a vertex in $X$. Clearly the following path is an $(X, Y)$-canonical $(H P, s, t)$ :

$$
P_{s} P_{x y}^{1} P_{x y}^{2} P_{x y}^{3} \ldots P_{x y}^{k} P_{x z}^{1} P_{x z}^{2} \ldots P_{x z}^{k-1} P_{t}
$$

Case 2. This case can be proved by arguments similar to those for proving the above case.
Case 3. If $s \in Y$, then either $P_{s}$ is a $Y$-path or $P_{s}=$ $P_{y} P^{\prime}$ where $P_{y}$ is a $Y$-path, $P^{\prime}$ does not visit any vertex in $Y$ and $P^{\prime}$ ends at a vertex in $Z$. In both cases, the following path is an $(X, Y)$-canonical $(H P, s, t)$ :

$$
P_{s} P_{x z}^{1} P_{x z}^{2} \ldots P_{x z}^{k-1} P_{x y}^{1} P_{x y}^{2} P_{x y}^{3} \ldots P_{x y}^{k}
$$

Case 4. Clearly, $P_{x y}^{1}=P_{x} P^{\prime \prime}$ where $P_{x}$ is an $X$-path and $P^{\prime \prime}$ starts from a vertex in $Y$. Let $P^{\prime}$ be the reverse path of the following path:

$$
P_{x z}^{1} P_{x z}^{2} \ldots P_{x z}^{k-1}
$$

Obviously, $P^{\prime}$ starts from a vertex in $Z$ and ends at vertex in $X$. Then, the following path is an $(X, Y)$ canonical ( $H P, s, t$ ):

$$
P_{x} P^{\prime} P^{\prime \prime} P_{x y}^{2} P_{x y}^{3} \ldots P_{x y}^{k}
$$

We use $P-t$ to denote the subpath $P^{\prime}$ of $P$ such that $P=P^{\prime} t$ and $t$ is the last vertex visited by $P$. We use $P-P^{\prime}$ to denote the subpath $P$ " of $P$ such that $P=P " P^{\prime}$. Let $\mathcal{P}$ be an $(X, Y)$-canonical $(H P, s, t)$
of $G$. Suppose $\mathcal{P}$ has $k(Y)$-maximal paths. For $1 \leq$ $i \leq k$, let $P_{x}^{i}$ and $P_{y}^{i}$ be ( $X$ )-maximal and ( $Y$ )-maximal path, respectively. For simplicity, we use $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ to denote the subpath of $\mathcal{P}$ obtained in all of the following three cases.
Case 1, both $s$ and $t$ are in $Y$.
In this case, without loss of generality, we assume that $\mathcal{P}=P_{y}^{1} P_{x x} P_{y}^{2} P_{x}^{1} \cdots P_{y}^{k-1} P_{x}^{k-2} P_{y}^{k}$ where $P_{y}^{1}$ starts from vertex $s, P_{y}^{k}$ ends at vertex $t, P_{x x}$ starts from a vertex in $X$ and ends at a vertex in $X$, does not visits any vertex in $Y$. Obviously one has $|X| \geq k \geq \pi_{2}(Y, s, t)$. We use $\mathcal{P}-Y$ to denote path $P_{x x} P_{x}^{1} P_{x}^{2} \cdots P_{x}^{k-2}$. Note that $\mathcal{P}-Y$ contains an $(X)$ path that visits at least $k-1$ vertices of $X$. We use $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ to denote the path obtained by removing the last $\left|X^{\prime}\right|$ vertices from path $\mathcal{P}-Y$. Since $X$ and $Z$ are joint, $X$ and $Y$ are joint, and $X$ is a clique, we may assume that $X^{\prime}$ is any subset of $X$ with $\left|X^{\prime}\right|$ less than or equal to the number of vertices visited by path $P_{x}^{1} P_{x}^{2} \cdots P_{x}^{k-2}$. It is easy to see that $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ starts from a vertex in $X$ and ends at a vertex in $X$.
Case 2, at most one of $s$ and $t$ is in $Y$.
Without loss of generality, assume that $t \in Y$. In this case,
$\mathcal{P}=P_{w} P_{y}^{1} P_{x}^{1} P_{y}^{2} P_{x}^{2} \cdots P_{y}^{k-1} P_{x}^{k-1} P_{y}^{k}$
where $P_{y}^{k}$ ends at vertex $t, P_{w}$ starts from $s$, ends at a vertex in $X$, does not visits any vertex in $Y$. Obviously, $k \geq \pi_{1}(Y, t)$ and $|X| \geq k \geq \pi_{1}(Y, t) \geq \pi_{0}(Y)$. In this case, we use $\mathcal{P}-Y$ to denote path $P_{w} P_{x}^{1} P_{x}^{2} \ldots P_{x}^{k-1}$. Note that $\mathcal{P}-Y$ contains an $(X)$-path that visits at least $k$ vertices of $X$. We use $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ to denote the path obtained by removing the last $\left|X^{\prime}\right|$ vertices from path $\mathcal{P}-Y$ with $\left|X^{\prime}\right|$ less than or equal to the number of vertices visited by path $P_{x}^{1} P_{x}^{2} \cdots P_{x}^{k-1}$. That is, $\mathcal{P}-$ $\left(X^{\prime} \cup Y\right)=(\mathcal{P}-Y)-P_{x}^{*}$ where the set of vertices visited by $P_{x}^{*}$ is $X^{\prime}$.
Case 3, neither $s$ nor $t$ is in $Y$.
In this case,
$\mathcal{P}=P_{w}^{1} P_{y}^{1} P_{x}^{1} P_{y}^{2} P_{x}^{2} \cdots P_{y}^{k-1} P_{x}^{k-1} P_{y}^{k} P_{w}^{2}$
where $P_{w}^{2}$ starts from a vertex in $X$, ends at vertex $t$, $P_{w}^{1}$ starts from $s$, ends at a vertex in $X$, neither $P_{w}^{1}$ nor $P_{w}^{2}$ visits any vertex in $Y$. Obviously, $k \geq \pi_{0}(Y)$ and $|X|>k \geq \pi_{0}(Y)$. In this case, we use $\mathcal{P}-Y$ to denote path $P_{w}^{1} P_{x}^{1} P_{x}^{2} \cdots P_{x}^{k-1} P_{w}^{2}$. Let $P_{w}^{1}$ ends at $x_{1}$ and $P_{w}^{2}$ starts from $x_{2}$. Path $x_{1} P_{x}^{1} P_{x}^{2} \cdots P_{x}^{k-1} x_{2}$ is an $(X)$ path that visits at least $k+1$ vertices. Let $X^{\prime}$ be the last $\left|X^{\prime}\right|$ vertices visited by path $x_{1} P_{x}^{1} P_{x}^{2} \cdots P_{x}^{k-1} x_{2}$. We use $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ to denote the path obtained from $\mathcal{P}-Y$ by removing the last $\left|X^{\prime}\right|$ vertices from path $x_{1} P_{x}^{1} P_{x}^{2} \cdots P_{x}^{k-1} x_{2}$ where $\left|X^{\prime}\right| \leq k$. That is, $\mathcal{P}-\left(X^{\prime} \cup Y\right)=\left(P_{w}^{1} P_{x}^{1} P_{x}^{2} \cdots P_{x}^{k-1}-P_{x}^{*}\right) P_{w}^{2}$ where the set of vertices visited by $P_{x}^{*}$ is $X^{\prime}$.

The concept of $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ will be frequently used in the proof of lemmas for developing our algorithm.

Lemma 3 (1) If $G$ has an ( $H P, s$ ), then $G$ has an $(H P, s)$ such that at most one of its endpoint is in $Y$. (2) If $G$ has an HP and $|X|>\pi_{0}(Y)$, then $G$ has an $H P$ such that neither of its two endpoints is in $Y$.
(3) If $|X|>\pi_{0}(Y), s \notin Y$, and $G$ has an ( $H P, s$ ), then there exists an $(H P, s)$ such that neither of its two endpoints is in $Y$.

Proof. (1) Suppose $\mathcal{P}$ is an $(H P, s)$ of $G$ that starts from $s$ and ends at $t$. If $t \notin Y$, then the lemma is true already. In the following, we assume tht both $s$ and $t$ are in $Y$. By Lemma 2, assume that $\mathcal{P}$ is $(X, Y)$ canonical and $\mathcal{P}=P_{y} P_{x z} P_{x y}$ where $P_{y}, P_{x z}$, and $P_{x y}$ are subpaths of $\mathcal{P}, P_{y}$ starts from $s, P_{x y}$ ends at $t, P_{x y}$ is an $(X, Y)$-maximal path, $P_{x z}$ starts from a vertex in $X$, ends at a vertex in $Z$ and does not visits any vertex in $Y$. Clearly, $P_{y} P_{x y} P_{x z}$ is an $(H P, s)$ such that its endpoint other than $s$ is not in $Y$.
(2) Suppose $\mathcal{P}$ is an $H P$ of $G$ such that $\mathcal{P}$ starts from $s$ and ends at $t$. If neither $s$ nor $t$ is in $Y$, then this statement is true. By statement (1) of this lemma, we may assume that $\mathcal{P}$ is an $H P$ of $G$ such that one of its endpoint is in $Y$ and the other of its endpoint is not in $Y$. Without loss of generality, assume that $t \in Y$ and $s \notin Y$. For notational convienence, let $k=\pi_{0}(Y)$. By Lemma 2, we may assume that $\mathcal{P}$ is an $(X, Y)$-canonical $H P$. Thus, $\mathcal{P}=P_{s} P_{x y}$ where $P_{x y}$ is an $(X, Y)$-maximal path. Since $Z \neq \emptyset, P_{s}$ ends at a vertex $z \in Z$. Consider graph $G\left[P_{x y}\right]$ which is the subgraph of $G$ induced by the vertices visited by path $P_{x y}$. Suppose $P_{s}$ visits a vertex in $X$. If $s \in X$, then $P_{x y} P_{s}$ in HP that starts from a vertex in $X$ and ends at a vertex in $Z$. Otherwise, let $P_{s}=P_{s}^{1} P_{s}^{2}$ where $P_{s}^{1}$ ends at vertex in $Z$ and $P_{s}^{2}$ starts from a vertex in $X$ and ends at a vertex in $Z$. Then, $P_{s}^{1} P_{x y} P_{s}^{2}$ is an HP whose endpoints are not in $Y$. In the following, we assume that $P_{s}$ does not visits any vertex in $X$. That is, $P_{x y}$ is an HP of $G[X \cup Y]$. Since $|X|>\pi_{0}(Y)$, there exists an HP, $P^{\prime}$, of $G[X \cup Y]$ such that $P^{\prime}=$ $P_{x} P_{y}^{1} x_{1} P_{y}^{2} x_{2} \cdots P_{y}^{k} x_{k}$ is an HP of $G\left[P_{x y}\right]$ where $x_{i}$ 's are vertices in $P_{x y} \cap X$ for $1 \leq i \leq k$ and $P_{x}$ is an $(X)$-path visits all vertices $X-\left\{x_{i}: 1 \leq i \leq k\right\}$. Then, $P_{s} P^{\prime}$ is an HP of $G$ whose endpoints are not in $Y$.

Though the following lemma is inspired by those given in [20], it is slightly different from the original form in [20] and leads to a more simple algorithm.

Lemma 4 Let $X^{\prime} \subset X$ and $G^{\prime}=G-\left(X^{\prime} \cup Y\right)$.
(1) If $G$ has an $H C$, then $|X| \geq \pi_{0}(Y)+1$.
(2) If $|X| \geq \pi_{0}(Y)+1$ and $\left|X^{\prime}\right|=\pi_{0}(Y)$, then $G$ has an $H C$ iff $G^{\prime}$ has an $H C$.

Proof. (1) Suppose $C$ is an $H C$ of $G$. Let $k$ be The number of $(Y)$-maximal paths in $C$. It is easy to see that $k \geq \pi_{0}(Y)$. To connect these $k(Y)$-maximal paths into an HC, there are at $k(V-Y)$-maximal paths in $C$. These $(V-Y)$-maximal paths starts from a vertex in $X$ and ends at a vertex in $X$. In other words, each of these $(V-Y)$-maximal paths visits at least one vertex in $X$. Since $Z \neq \emptyset$, at least one of these $(V-Y)$-maximal paths visits a vertex in $Z$. A $(V-Y)$-maximal path that visits a vertex in $Z$ visits at least two vertices in $X$. Thus, $|X|>k$.
(2) Suppose $G$ has an HC. It is easy to see that $G$ has an HP, denoted by $\mathcal{P}$, that starts from a vertex $s \in Z$ and ends at a vertex $t \in X$ where $s$ and $t$ are adjacent in $G$. Obviously, $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an HP of $G^{\prime}$. Hence $G^{\prime}$ has an HC.

Conversely, suppse $G^{\prime}$ has an HC. Then, $G^{\prime}$ has an HP, denoted by $\mathcal{P}^{*}$ that starts from a vertex in $x$ and ends at a vertex in $Z$. By the definition of $X$ and $Y$, there exists an HP, denoted by $\mathcal{P}^{\prime}$, of $G\left[X^{\prime} \cup Y\right]$ that starts from a vertex in $X$ and ends at a vertex in $Y$. Clearly, $\mathcal{P}^{\prime} \mathcal{P}^{*}$ is an HP of $G$. Since $X$ and $Z$ are joint, $G$ has an HC.

Now, we can explain the basic ideas of the algorithms. If $G$ is a cograph, then we can solve the HC problem by the algorithm given in [8]. By Theorem 1 , we can find vertex sets $X, Y$, and $Z$ satisfying the conditions given at the begining of this section. By Lemma 4, we can solve the HC problem for $G$ by solving the HC problem for $G^{\prime}$ where the number of vertices of $G^{\prime}$ is less than that of $G$. By repeatedly applying Lemma 4, eventually $G^{\prime}$ becomes a cograph. This leads to a polynomial time algorithm for the HC problem in Ptolemaic graphs. The time complexity of this algorithm depends on how fast we can find vertex sets $X$ and $Y$. Theorem 1 suggests a very efficient implementation for computing vertex sets $X$ and $Y$ by using a hanging of $G$. A hanging of $G$ can be computed in $O(n+m)$ time. Suppose $G$ has a hanging $h_{u}$ at vertex $u$ such as $L_{0}(u), L_{1}(u), \ldots, L_{t}(u)$. Then, $X$ will be a subset of $L_{t-1}(u)$ and $Y$ will be a subset of $L_{t}(u)$. Since we delete vertices in $X^{\prime}$ and $Y$ to obtain $G^{\prime}$, we can obtain a hanging for $G^{\prime}$ from the hanging of $G$ in $O\left(\left|X^{\prime}\right|+|Y|\right)$ time where $X^{\prime}$ is the set of vertices in $X$ that are removed to obtained $G^{\prime}$. This leads to a linear time algorithm for the HC problem in Ptolemaic graphs. In the following, we prove lemmas necessary for developing our algorithm for the HP, $(H P, s)$, and ( $H P, s, t$ ) problems in Ptolemaic graphs by using the same approach.

Lemma 5 Let $X^{\prime} \subset X, s^{\prime} \in X-X^{\prime}$, and $G^{\prime}=G-$ $\left(X^{\prime} \cup Y\right)$.
(1) If $G$ has an $H P$, then $|X| \geq \pi_{0}(Y)$.
(2) Suppose $|X|=\pi_{0}(Y)$ and $\left|X^{\prime}\right|=\pi_{0}(Y)-1$.

Then, $G$ has an $H P$ iff $G^{\prime}$ has an $\left(H P, s^{\prime}\right)$.
(3) Suppose $|X|>\pi_{0}(Y)$ and $\left|X^{\prime}\right|=\pi_{0}(Y)$.

Then, $G$ has an $H P$ iff $G "$ has an $H P$.

## Proof.

(1) This statement can be proved by arguments similar to those for proving statement (1) of Lemma 4.
(2) Suppose $\mathcal{P}$ is an $H P$ of $G$. By arguments similar to those for proving statement (1) of Lemma 4, we can prove that $|X|>\pi_{0}(Y)$ if both endpoints of $\mathcal{P}$ is not in $Y$. Thus, at least one endpoint of $\mathcal{P}$ is in $Y$. By statement (1) of Lemma 3, we may assume that $\mathcal{P}$ has one endpoint in $Y$ and the other endpoint not in $Y$. Withoout loss of generality, assume that $\mathcal{P}$ starts from $s$ and ends at vertex $t$ in $Y$. By Lemma 2, we may assume that $\mathcal{P}$ is $(X, Y)$-canonical. Thus, $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an HP of $G^{\prime}$. Besides, $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ ends at a vertex in $X$ since $\left|X^{\prime}\right|=\pi_{0}(Y)-1$. In other words, $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an $\left(H P, s^{\prime}\right)$ of $G^{\prime}$.

Conversely, suppose $\mathcal{P}^{\prime}$ is an $\left(H P, s^{\prime}\right)$ of $G^{\prime}$ and $\mathcal{P}^{\prime}$ ends at vertex $s^{\prime}$. Since $\left|X^{\prime}\right|=\pi_{0}(Y)-1$ and $X$ and $Y$ are joint, there is an $H P$, denoted by $\mathcal{P}^{\prime \prime}$, of $G\left[X^{\prime} \cup Y\right]$ with both endpoints in $Y$. Thus, $\mathcal{P}^{\prime} \mathcal{P}^{\prime \prime}$ is an $H P$ of $G$.
(3) Suppose $\mathcal{P}$ is an $H P$ of $G$ where $\mathcal{P}$ starts from $s$ and ends at $t$. By Lemma 3 (2), neither $s$ nor $t$ is in $Y$. By Lemma 2, assume that $\mathcal{P}$ is $(X, Y)$-canonical. Hence $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an HP of $G^{\prime}$.

Conversely, suppose $\mathcal{P}^{\prime}$ is an $H P$ of $G^{\prime}$. Since $\left|X^{\prime}\right|=$ $\pi_{0}(Y)$, there is an $H P$, denoted by $\mathcal{P}^{\prime \prime}$, of $G\left[X^{\prime} \cup Y\right]$ with one endpoint in $X^{\prime}$ and the other endpoint in $Y$. Since $X-X^{\prime}$ and $Z$ are not empty, there is an edge $(x, z)$ in $\mathcal{P}^{\prime}$ with $x \in X$ and $z \in Z$. Let $\mathcal{P}^{\prime}=P_{1} P_{2}$ such that $P_{1}$ ends at a vertex in $Z$ and $P_{2}$ starts from a vertex in $X$. Then, $P_{1} \mathcal{P} " P_{2}$ is an HP of $G$.

Lemma 6 Suppose $G$ has an $(H P, s)$.
(1) If $s \in Y$, then $|X| \geq \pi_{1}(Y, s)$.
(2) If $s \in X$, then $|X|>\pi_{0}(Y)$.
(3) If $s \in V-(X \cup Y)$, then $|X| \geq \pi_{0}(Y)$.

Proof. This statement can be proved by arguments similar to those for proveing statement (1) of Lemma 4.

Lemma 7 Let $X^{\prime} \subset X, s^{\prime} \in X-X^{\prime}$, and $G^{\prime}=$ $G-\left(X^{\prime} \cup Y\right)$.
(1) Suppose $s \in Y,|X| \geq \pi_{1}(Y, s)$ and $\left|X^{\prime}\right|=$ $\pi_{1}(Y, s)-1$.
Then, $G$ has an $(H P, s)$ iff $G^{\prime}$ has a $\left(H P, s^{\prime}\right)$.
(2) Suppose $s \notin(X \cup Y),|X|=\pi_{0}(Y)$ and $\left|X^{\prime}\right|=$
$\pi_{0}(Y)-1$.
Then, $G$ has an $(H P, s)$ iff $G^{\prime}$ has an (HP, $\left.s, s^{\prime}\right)$.
(3) Suppose $s \notin Y,|X| \geq \pi_{0}(Y)+1$ and $\left|X^{\prime}\right|=\pi_{0}(Y)$. Then, $G$ has an $(H P, s)$ iff $G^{\prime}$ has an $(H P, s)$.
Proof. (1) Suppose $\mathcal{P}$ is an $(H P, s)$ of $G$. By Lemma 3 (3), we may assume that at most one endpoint of $\mathcal{P}$ is in $Y$. Withoout loss of generality, assume that $\mathcal{P}$ starts from $t$ not in $Y$ and ends at vertex $s$ in $Y$. By Lemma 2 , we may assume that $\mathcal{P}$ is $(X, Y)$-canonical. Thus, $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an HP of $G^{\prime}$. Since $\left|X^{\prime}\right|=\pi_{1}(Y, s)-1$ and $\mathcal{P}$ has at least $\pi_{1}(Y, s)(Y)$-maximal paths, $\mathcal{P}-$ $\left(X^{\prime} \cup Y\right)$ ends at a vertex in $X$. By the definition of $X, Y$, and $Z$, we may assume that $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ ends at vertex $s^{\prime}$.
Conversely, suppose $\mathcal{P}^{\prime}$ is an $\left(H P, s^{\prime}\right)$ of $G^{\prime}, \mathcal{P}^{\prime}$ starts from $s^{\prime} \in X-X^{\prime}$, and $\left|X^{\prime}\right|=\pi_{1}(Y, s)-1$. Since $X$ is a clique and $X$ and $Y$ are joint, there is an HP, denoted by $\mathcal{P}^{\prime \prime}$, of $G\left[X^{\prime} \cup Y\right]$ such that $\mathcal{P}^{\prime \prime}$ starts from $s$, ends at a vertex in $Y$. Thus, $\mathcal{P}^{\prime \prime} \mathcal{P}^{\prime}$ is an $(H P, s)$ of $G$ since $X$ and $Y$ are joint.
(2) Suppose $\mathcal{P}$ is an $(H P, s)$ of $G$. By Lemma 2, we may assume that $\mathcal{P}$ is $(X, Y)$-canonical ( $H P, s$ ), starts from vertex $s$ and ends at a vertex $t$. Path $\mathcal{P}$ has at least $\pi_{0}(Y)(Y)$-maximal paths. Since $|X|=\pi_{0}(Y, s)$ and $Z \neq \emptyset$, we have that $t \in Y$. Thus, $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an HP of $G^{\prime}$. Since $\left|X^{\prime}\right|=\pi_{0}(Y)-1$ and $\mathcal{P}$ has at least $\pi_{0}(Y)(Y)$-maximal paths, $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ ends at a vertex in $X$. By the definition of $X, Y$, and $Z$, we may assume that $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ ends at vertex $s^{\prime}$. In other words, $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an $\left(H P, s, s^{\prime}\right)$ of $G^{\prime}$.

Conversely, by arguments similar to those for proving statement (1), we can show that if $G^{\prime}$ has an (HP,s, $s^{\prime}$ ), then $G$ has an (HP,s).
(3) Suppose $\mathcal{P}$ is an $(H P, s)$ of $G$. By Lemma 3 (3) and 2 , we may assume that $\mathcal{P}$ is $(X, Y)$-canonical $(H P, s)$ and neither of its endpoints is in $Y$. Hence $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an $(H P, s)$ of $G^{\prime}$.

Conversely, suppose $\mathcal{P}^{\prime}$ is an $(H P, s)$ of $G^{\prime}$. Since $Z \neq \emptyset$, we have that $\mathcal{P}^{\prime}=P_{1} P_{2}$ such that $P_{1}$ ends at a vertex in $Z$ and $P_{2}$ starts from a vertex in $X$. Since $\left|X^{\prime}\right|=\pi_{0}(Y)$, there is an $H P$, denoted by $\mathcal{P}^{\prime \prime}$, of $G\left[X^{\prime} \cup Y\right]$ such that $\mathcal{P}$ " starts from a vertex in $X$ and ends at a vertex in $Y$. Thus, $P_{1} \mathcal{P}^{\prime \prime} P_{2}$ is an $(H P, s)$ of $G$ since $X$ and $Y$ are joint and $X$ and $Z$ are joint.

Lemma 8 Suppose $G$ has an ( $H P, s, t$ ).
(1) If $\{s, t\} \subseteq Y$, then $|X| \geq 2$ and $|X| \geq \pi_{2}(Y, s, t)$.
(2) If $s \in Y$ and $t \notin Y$, then $|X-t| \geq \pi_{1}(Y, s)$.
(3) If $s \in X$ and $t \notin Y$, then $|X-s-t| \geq \pi_{0}(Y)$.
(4) If $\{s, t\} \cap(X \cup Y)=\emptyset$, then $|X| \geq \pi_{0}(Y)+1$.

Proof. This statement can be proved by arguments similar to those for proveing statement (1) of Lemma 4.

Lemma 9 Let $X^{\prime} \subset X, s \notin X^{\prime}, t \notin X^{\prime}, G^{\prime}=$ $G-\left(X^{\prime} \cup Y\right)$, and $s^{\prime}$ and $t^{\prime}$ be any two distinct vertices in $X-X^{\prime}$.
(1) Suppose $\{s, t\} \subseteq Y, \pi_{2}(Y, s, t)=1,|X| \geq 2$.

Then, $G$ has an $(H P, s, t)$ iff $G[V-Y]$ has an (HP, $\left.s^{\prime}, t^{\prime}\right)$.
(2) Suppose $\{s, t\} \subseteq Y, \pi_{2}(Y, s, t)>1,|X| \geq$ $\pi_{2}(Y, s, t)$ and $\left|X^{\prime}\right|=\pi_{2}(Y, s, t)-2$.
Then, $G$ has an $(H P, s, t)$ iff $G^{\prime}$ has an $\left(H P, s^{\prime}, t^{\prime}\right)$.
(3) Suppose $t \in Y$, $s \notin Y,|X-s| \geq \pi_{1}(Y, t)$, and $\left|X^{\prime}\right|=\pi_{1}(Y, t)-1$.
Then, $G$ has an $(H P, s, t)$ iff $G^{\prime}$ has an $\left(H P, s, t^{\prime}\right)$.
(4) Suppose $\{s, t\} \cap Y=\emptyset,|X| \geq \pi_{0}(Y)+1,|X-s-t| \geq$ $\pi_{0}(Y)$ and $\left|X^{\prime}\right|=\pi_{0}(Y)$.
Then, $G$ has an $(H P, s, t)$ iff $G^{\prime}$ has an $(H P, s, t)$.
Proof. (1) Suppose $\mathcal{P}$ is an HP of $G$. By the definition of $X$ and $Y$, we may let

$$
\mathcal{P}=P_{y}^{1} P_{x x}^{1} P_{y}^{2} P_{x x}^{2} \cdots P_{y}^{k-1} P_{x x}^{k-1} P_{y}^{k}
$$

where each $P_{y}^{i}$ is a $(Y)$-maximal path and each $P_{x x}^{i}$ does not visits any vertex in $Y$, starts from a vertex in $X$ and ends at a vertex in $X$. It is easy to see that $P_{x x}^{1} P_{x x}^{2} \cdots P_{x x}^{k-1}$ is an $H P$ of $G^{\prime}$ with both endpoints in $X$ which can be replaced by $s^{\prime}$ and $t^{\prime}$. Thus $G^{\prime}$ has an ( $H P, s^{\prime}, t^{\prime}$ ). Conversely, suppose $\mathcal{P}^{\prime}$ is an $\left(H P, s^{\prime}, t^{\prime}\right)$ of $G^{\prime}$. Since $\pi_{2}(Y, s, t)=1$, there is an $(H P, s, t), \mathcal{P}^{\prime \prime}$, of $G[Y]$. Let $\mathcal{P}^{\prime \prime}=s \mathcal{P}^{*}$. Then, $s \mathcal{P}^{\prime} \mathcal{P}^{*}$ is an $(H P, s, t)$ of $G$, since $X$ and $Y$ are joint.
(2) Suppose $\mathcal{P}$ is an HP of $G$. By Lemma 2, we may assume that $\mathcal{P}$ is an $(X, Y)$-canonical $(H P, s, t)$. Path $\mathcal{P}$ has at least $\pi_{2}(Y, s, t)(Y)$-maximal paths. Since $\left|X^{\prime}\right|=\pi_{2}(Y, s, t)-2, \mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an $H P$ of $G^{\prime}$ with both endpoints in $X-X^{\prime}$ which can be replaced by $s^{\prime}$ and $t^{\prime}$. Thus $G^{\prime}$ has an $\left(H P, s^{\prime}, t^{\prime}\right)$.

Conversely, suppose $\mathcal{P}^{\prime}$ is an $\left(H P, s^{\prime}, t^{\prime}\right)$ of $G^{\prime}$. Since $\left|X^{\prime}\right|=\pi_{2}(Y, s, t)-2$, we can cover $G\left[X^{\prime} \cup Y\right]$ by two vertex disjoint paths $\mathcal{P}_{1}$ and $\mathcal{P}_{2}$ with all their endpoints in $Y$ such that $\mathcal{P}_{1}$ starts from vertex $s$, and $\mathcal{P}_{2}$ ends at vertex $t$. Thus, $\mathcal{P}_{1} \mathcal{P}^{\prime} \mathcal{P}_{2}$ is an $(H P, s, t)$ of $G$, since $X$ and $Y$ are joint.
(3) Suppose $G$ has an $(H P, s, t)$. By Lemma 2, we may assume that it is $(X, Y)$-canonical. Since $\left|X^{\prime}\right|=$ $\pi_{1}(Y, t)-1$, path $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an HP of $G^{\prime}$ that starts from vertex $s$, ends at a vertex in $X$ which can be replaced by vertex $t^{\prime}$. In other words, $\mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an $\left(H P, s, t^{\prime}\right)$ of $G^{\prime}$. Thus $G^{\prime}$ has an $\left(H P, s, t^{\prime}\right)$.

Conversely, suppose $\mathcal{P}^{\prime}$ is an ( $H P, s, t^{\prime}$ ) of $G^{\prime}$ that starts from vertex $s$ and ends at vertex $t^{\prime}$. Since $\left|X^{\prime}\right|=$ $\pi_{1}(Y, t)-1$, there is an $(H P, t) \mathcal{P}^{\prime \prime}$ of $G\left[X^{\prime} \cup Y\right]$ with both endpoints in $Y$. Thus, $\mathcal{P}^{\prime} \mathcal{P}^{\prime \prime}$ is an $(H P, s, t)$ of $G$, since $X$ and $Y$ are joint.
(4) Suppose $G$ has an $(H P, s, t)$. By Lemma 2, we may assume that it is $(X, Y)$-canonical. Since $\{s, t\} \cap$
$Y=\emptyset$, and $\left|X^{\prime}\right|=\pi_{0}(Y), \mathcal{P}-\left(X^{\prime} \cup Y\right)$ is an $(H P, s, t)$ of $G^{\prime}$.

Conversely, suppose $\mathcal{P}^{\prime}$ is an $(H P, s, t)$ of $G^{\prime}$. Since $\left|X^{\prime}\right|=\pi_{0}(Y)$, there is an $H P$, denoted by $\mathcal{P}$ ", of $G\left[X^{\prime} \cup Y\right]$ that starts from a vertex in $X$ and ends at a vertex in $Y$. Note that there exist vertices $x \in\left(X-X^{\prime}\right)$ and $z \in Z$ such that $(x, z)$ is an edge of $\mathcal{P}^{\prime}$, since $\left(X-X^{\prime}\right)$ and $Z$ are not empty. Let $\mathcal{P}^{\prime}=P_{1} P_{2}$ such that $P_{1}$ ends at a vertex in $Z$ and $P_{2}$ starts from a vertex in $X$. Thus, $P_{1} \mathcal{P} " P_{2}$ is an $(H P, s, t)$ of $G$, since $X$ and $Y$ are joint.

In light of previous lemmas and theorem, we have the algorithm shown in Figure 1. for the Hamiltonian path problem on Ptolemaic graphs.

Theorem 10 Algorithm HP-pt solves the Hamiltonian path problem for Ptolemaic graphs in linear time.

Proof. In the algorithm shown in Figure 1, we build the hanging $h_{u}$ by a breadth-first search, and use bucket sort to sort $\mathcal{F}$. Next, since all the three parameters $\pi_{0}(H), \pi_{1}(H, s)$ and $\pi_{2}(H, s, t)$ can be determined in linear time for any cograph $H$ [8, 17, 20]. Thus each level $L_{i}$ is emptied during the $i$-th iteration of the "for" loop in $O\left(\left|L_{i}\right|+\left|E\left(G\left[L_{i}\right]\right)\right|\right)$ time. So the linearity of the whole algorithm follows. Finally, the correctness of the algorithm follows from Lemma 5 to 9 .

With the aid of previous lemmas and corollary, one can easily modify algorithm HP-pt to conclude the following corollary.

Corollary 11 There exists a linear-time algorithm for determining whether or not a Ptolemaic graph $G$ has an $H C$ (respectively, $(H P, s),(H P, s, t)$ for any vertices $s$, $t$ in $G)$.

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Algorithm HP-pt. Determine whether or not a connected Ptolemaic graph has a $H P$.
Input: A connected Ptolemaic graph $G=(V, E)$.
Output: Determine whether or not $G$ has a Hamiltonian path.
Method.

```
\(C \leftarrow \emptyset ; p \leftarrow 0 ;\)
determine the hanging \(h_{u}=\left(L_{0}, L_{1}, \ldots, L_{f}\right)\) of \(G\) at a vertex \(u\);
for \(i=f\) to 1 step -1 do
\(\left\{\right.\) let \(\mathcal{F}=\left\{A_{1}, A_{2}, \ldots, A_{j}\right\}\) be the components of \(G\left[L_{i}\right]\);
    sort \(\mathcal{F}\) such that \(\left|N_{L_{i-1}}\left(A_{i_{1}}\right)\right| \leq\left|N_{L_{i-1}}\left(A_{i_{2}}\right)\right| \leq \ldots \leq\left|N_{L_{i-1}}\left(A_{i_{j}}\right)\right|\);
    if \(i=1\) then \(\left\{j \leftarrow 1 ; A_{i_{1}} \leftarrow L_{1}+u\right.\); \(\}\)
    for \(k=1\) to \(j\) do
    \(\left\{Y \leftarrow A_{i_{k}} ; X \leftarrow N_{L_{i-1}}(Y)\right.\);
    Case 1: \(C=\emptyset\)
        if \(i=1\) and \(\pi_{0}(Y) \neq 1\) then GOTO \(\left(^{*}\right)\);
        if \(|X|<\pi_{0}(Y)\) then GOTO \(\left.{ }^{*}\right)\) else \(\left\{\right.\) if \(|X|=\pi_{0}(Y)\) then \(p \leftarrow \pi_{0}(Y)-1\) else \(\left.p \leftarrow \pi_{0}(Y) ;\right\}\)
        let \(X^{\prime}\) be any subset of \(X\) with \(\left|X^{\prime}\right|=p\) and \(s^{\prime} \in\left(X-X^{\prime}\right)\);
        if \(p=\pi_{0}(Y)-1\) then \(C \leftarrow\left\{s^{\prime}\right\}\);
    Case 2: \(|C|=1(\) say \(C=\{s\})\)
        if \(i=1\) then \(\pi_{1}(Y, s) \neq 1\) then GOTO \(\left(^{*}\right)\);
        if \(s \in Y\) then \(\left\{\right.\) if \(|X|<\pi_{1}(Y, s)\) then GOTO \(\left(^{*}\right)\) else \(\left.p \leftarrow \pi_{1}(Y, s)-1 ;\right\}\)
        if \(\left(s \notin Y\right.\) and \(\left.|X|<\pi_{0}(Y)\right)\) or \(\left(s \in X\right.\) and \(\left.|X|=\pi_{0}(Y)\right)\) then GOTO \(\left(^{*}\right)\);
        if \(s \notin(X \cup Y)\) and \(|X|=\pi_{0}(Y)\) then \(p \leftarrow \pi_{0}(Y)-1\);
        if \(s \notin Y\) and \(|X| \geq \pi_{0}(Y)+1\) then \(p \leftarrow \pi_{0}(Y)\);
        let \(X^{\prime}\) be any subset of \(X\) with \(\left|X^{\prime}\right|=p\) and \(t^{\prime} \in\left(X-X^{\prime}-C\right)\);
        if \(p=\pi_{1}(Y, s)-1\) then \(C \leftarrow\left\{t^{\prime}\right\}\) else \(\left\{\right.\) if \(p=\pi_{0}(Y)-1\) then \(\left.C \leftarrow\left\{s, t^{\prime}\right\} ;\right\}\)
    Case 3: \(|C|=2\) (say \(C=\{s, t\}\) and w.l.o.g. say \(s \in Y\) as \(|C \cap Y|=1\) )
            if \(i=1\) and \(\pi_{2}(Y, s, t) \neq 1\) then GOTO \(\left(^{*}\right)\);
            if \(C \subseteq Y\) and \(\left(|X|<2\right.\) or \(\left.|X|<\pi_{2}(Y, s, t)\right)\) then GOTO \(\left(^{*}\right)\);
            if \(|C \cap Y|=1\) and \(|X-s-t| \geq \pi_{1}(Y, s)\) then GOTO (*);
            if \(|C \cap X| \geq 1\) and \(C \cap Y=\emptyset\) and \(|X-s-t| \geq \pi_{0}(Y)\) then GOTO \(\left(^{*}\right)\);
            if \(C \cap(X \cup Y)=\emptyset\) and \(|X| \geq \pi_{0}(Y)+1\) then GOTO \(\left(^{*}\right)\);
            if \(C \subseteq Y\) and \(\pi_{2}(Y, s, t)=1\) and \(|X| \geq 2\) then \(p \leftarrow 0\);
            if \(C \subseteq Y\) and \(\pi_{2}(Y, s, t)>1\) and \(|X| \geq \pi_{2}(Y, s, t)\) then \(p \leftarrow \pi_{2}(Y, s, t)-2\);
            if \(|C \cap Y|=1\) and \(|X-t| \geq \pi_{1}(Y, s)\) then \(p \leftarrow \pi_{1}(Y, s)-1\);
            if \(C \cap Y=\emptyset\) and \(|X| \geq \pi_{0}(Y)+1\) and \(|X-C| \geq \pi_{0}(Y)\) then \(p \leftarrow \pi_{0}(Y)\);
            let \(X^{\prime}\) be any subset of \(X\) with \(\left|X^{\prime}\right|=p\) and \(s^{\prime}, t^{\prime} \in\left(X-X^{\prime}-C\right)\);
            if \(p=0\) or \(p=\pi_{2}(Y, s, t)-2\) then \(C \leftarrow\left\{s^{\prime}, t^{\prime}\right\}\) else \(\left\{\right.\) if \(p=\pi_{1}(Y, s)-1\) then \(\left.C \leftarrow\left\{s^{\prime}, t\right\} ;\right\}\)
    \(\left.L_{i-1} \leftarrow L_{i-1}-X^{\prime} ;\right\}\)
\}
    print "G has Hamiltonian path"; exit;
\({ }^{*}\) ) print "G has no Hamiltonian path";
```

Figure 1: The algorithm for the Hamiltonian path on Ptolemaic grpahs


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